Stochastic subgradient method converges on tame functions¹

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¹ Joint work with Dima Drusvyatskiy (UW), Sham Kakade (UW), and Jason Lee (Princeton) Foundations of Computational Mathematics (2019)

²https://people.orie.cornell.edu/dsd95/

Guiding Question

Is there a unified way to understand asymptotic convergence in nonsmooth and nonconvex (stochastic) optimization?

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Many have contributed.

Belenkiy, Bertsekas, Burke, Demyanov, Duchi, Ermoliev, Gaivoronski,
 Goffin, Gupal, Juditsky, Kiwiel, Lan, Lemaréchal, Lewis, Mifflin,
 Mikhalevich, Nemirovski, Nesterov, Norkin, Nurminskii, Overton, Polyak,
 Pshenichny, Rubinov, Rucinski, Sagastizábal, Shapiro, Shor, Uryasev....

Problem Class and Algorithms I

Problem. Minimize locally Lipschitz function

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where ∂f denotes Clarke subdifferential:

$$\partial f(x) = \operatorname{conv} \left\{ \lim_{x_i \to x} \nabla f(x_i) : x_i \to x \text{ in } \operatorname{dom}(\nabla f) \right\}.$$

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• Clipped proximal subgradient method if $f \ge 0$ (Duchi-Ruan '18)

Choose
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• And stochastic variants of previous algorithms....

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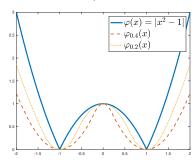
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- ightharpoonup arphi weakly convex \implies Moreau envelope

$$\varphi_{\lambda}(x) = \inf_{y} \left\{ \varphi(y) + \frac{1}{2\lambda} \|y - x\|^{2} \right\}$$

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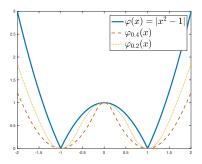


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Challenge: No clear Lyapunov function in general.

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- Lyapunov Assumption.
 - Strict Descent. We force φ to be Lyapunov for dynamics.

$$\left\{ \begin{array}{l} -\dot{z} \in G(z) \text{ a.e.} \\ z(0) \text{ not critical.} \end{array} \right\} \implies \varphi(z(t)) < \varphi(z(0)) \quad \forall t > 0$$

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Thm: Lyapunov \implies every limit point x^* of $\{x_k\}$ is critical.

(Kushner-Yin '03, Benaïm-Hofbauer-Sorin '05)

$$x_{k+1} = x_k - \alpha_k(y_k + \xi_k).$$

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3. Approximate evaluations

$$x_{k_j} \to x \qquad \Longrightarrow \qquad \frac{1}{n} \sum_{k=1}^n y_{k_j} \to G(x).$$

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4. Noise sequence $\{\xi_k\}$ satisfies

$$\sum_{k=1}^{\infty} \alpha_k \xi_k \text{ exists.}$$

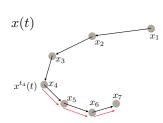
(Kushner-Yin '03, Benaïm-Hofbauer-Sorin '05, Duchi-Ruan '17)

Interpolation.

x(t) linearly interpolates $\{x_k\}$

Time-shifted curve.

$$x^{\tau}(\cdot) = x(\tau + \cdot).$$

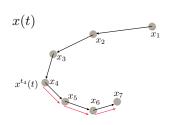


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Thm: For any $\tau_k \to \infty$, the set $\{x^{\tau_k}(\cdot)\}$ is compact in $\mathcal{C}(\mathbb{R}_+, \mathbb{R}^d)$, and all limit points $z(\cdot)$ are arcs satisfying

$$-\dot{z}(t) \in G(z(t))$$
 for a.e. $t \ge 0$.

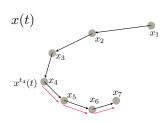
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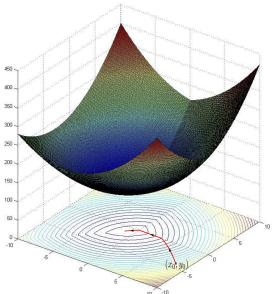
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Why Matter? If $x_{k_j} \to x^*$, then a limiting arc begins at limit point.

Strict Descent

When does φ strictly decrease along dynamics $-\dot{z} \in G(z)$?



A Sufficient Condition for Strict Descent

Intuition. Dynamics "should" decrease φ in proportion to square of "gradient."

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 $\begin{array}{ll} \textbf{Intuition.} & \textbf{Dynamics "should" decrease} \\ \varphi & \textbf{in proportion to square of "gradient."} \\ \end{array}$

Sufficient Condition. A chain rule: for any arc z, we have for a.e. t

$$(\varphi \circ z)'(t) = \langle G(z(t)), \dot{z}(t) \rangle$$

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Lemma: Suppose φ admits a chain rule and an arc $z(\cdot)$ satisfies

$$-\dot{z}(t) \in G(z(t))$$
 for a.e. $t \ge 0$.

Then

$$\|\dot{z}(t)\| = \text{dist}(0, G(z(t)))$$
 a.e.

and therefore

$$\varphi(z(0)) - \varphi(z(t)) = \int_0^t \operatorname{dist}^2(0; G(z(\tau))) d\tau, \quad \forall t \ge 0.$$

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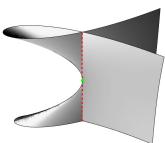
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Whitney stratifiable (D-Drusvyatskiy-Kakade-Lee '18)

Informally: Graph decomposes into manifolds, fit together in reg. pattern.



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- Definable functions. Any function with graph definable in o-minimal structure
 - Polynomials, $x^{1/r}$, $\lambda(X)$, $\max\{0,t\}$, $\log(1+e^t)$, and their sums, products, compositions are definable.
 - Any deep network built from definable pieces.

(van den Dries-Miller '96, Ta Lê Loi '97)

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- Stratify. Domain of φ stratifies into manifolds M_1,\dots,M_n such that $\varphi\big|_{M_*} \text{ is smooth.}$

- Local Chain Rule. On each manifold $\varphi\big|_{M_i}$ admits chain rule.
- Glue Along Arc. Glue all chain rules along arc $-\dot{z} \in G(z)$ using "Whitney condition" and projection formula of (Daniilidis-Bolte-Lewis-Shiota '07).

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For a stratifiable problem, a.s. all limit points x^* of stochastic proximal subgradient iterates $\{x_k\}$ are critical.

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- Similar result and technique apply to "discretizations" of $-\dot{z} \in G(z)$.
- Not true for general Lipschitz problems.
- The result is entirely geometric, independent of problem presentation.

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 - Applications of Chain Rule to Deep Learning.
 - (Du, Hu, Lee '18), (Castera-Bolte-Févotte-Pauwels '19), (Lyu-Li '19)

Broader Perspectives for Nonsmooth Optimization in Data Science

Qualitative Guarantees?

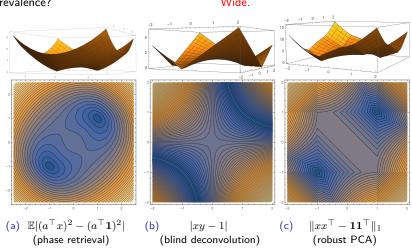
Stratifiable Functions.

Quantitative Guarantees?

Weakly convex.

Prevalence?

Wide.



Quantitative Guarantees and Consequences for Data Science

Weakly Convex

(D-Drusvyatskiy '18)

Sublinear Rates of Moreau Envelope

$$\mathbb{E}\left[\|\nabla\varphi_{\lambda}(x_{k^*})\|\right] = O(k^{1/4})$$

Key: Moreau (almost) Lyapunov

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Weakly Convex + Sharp growth

$$\varphi(x) - \inf_{\mathcal{X}} \varphi \ge \mu \cdot \operatorname{dist}(x, \mathcal{X}^*)$$

(D-Drusvyatskiy '18, '19)

Deterministic/Stochastic Linear Rates

$$\operatorname{dist}(x_k, \mathcal{X}^*) = O\left(\left(1 - \frac{\mu^2}{L^2}\right)^k\right)$$

Key: geometrically decaying stepsize.

Quantitative Guarantees and Consequences for Data Science

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In Practice

Robust phase retrieval, blind deconvolution, low-rank matrix recovery (Eldar-Mendelson '12) (Duchi-Ruan '18) (Charisoplous-D-Diaz-Drusvyatskiy '19) (Li, Zhu, So, Vidal '19)

Weakly Convex + Sharp Growth w.h.p.

Optimal guarantees with out-of-the-box subgradient method

Ex. Phase Retrieval & Blind Deconv cost O(md).

Summary

- Generic procedure for analyzing discretization schemes of $-\dot{z} \in G(z)$, including stochastic proximal subgradient algorithm.
- Convergence reduced to checking natural property of loss function.
- Identified strict descent, Sard property, and chain rule as key to convergence—automatic for stratifiable losses.

Thanks!