

Lecture 6

Lecturer: Damek Davis

Scribe: Angela Zhou

# 1 Recap

- Every bounded polyhedron is a polytope; we proved this using set polars and the separating hyperplane theorem.
- The **normal cone** of a closed, convex set  $S \subseteq \mathbb{R}^n$  is defined as

$$N_S : \mathbb{R}^n \rightarrow 2^{\mathbb{R}^n}$$

(power set on all points).

$$N_S(x) = \begin{cases} \{g \in \mathbb{R}^n \mid (\forall z \in S) \ g^T(z - x) \leq 0\} & \text{if } x \in S \\ \emptyset & \text{if } x \notin S \end{cases}$$

Normal cones characterize

- interiors and boundaries of convex sets:

$$N_S(x) = 0 \iff x \in \text{int}(S) \text{ and } N_S(x) \supsetneq \{0\} \iff x \in \partial S,$$

- Normal cones characterize projections:  $X = P_S(y) \iff y - x \in N_S(x)$ .

**Theorem 1 (General Optimality Conditions)** *Let  $S \subseteq \mathbb{R}^n$  be a nonempty, closed, convex set and let  $c \in \mathbb{R}^n$ . Then the following are equivalent:*

1.  $x^*$  solves:

$$\max_{x \in S} c^T x \tag{1}$$

2.  $c \in N_S(x^*)$

3.  $x^* = P_S(x^* + c)$

**Proof:** Observe that  $x^*$  solves (1) if, and only if,  $c^T(x - x^*) \leq 0$  which is true if, and only if,  $c \in N_S(x^*)$ . The inclusion  $c \in N_S(x^*)$  holds if, and only if,  $c = x^* + c - x^* \in N_S(x^*)$ , which is true if, and only if,  $x^* = P_S(x^* + c)$ . □

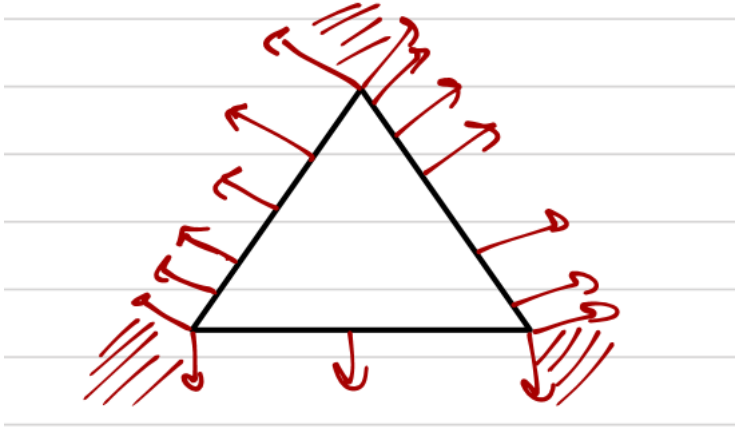
The following Corollary shows that bounded convex sets are round: whichever direction you pick, you can always find a point where that direction is in the normal cone.

**Lemma 2** *Let  $c \in \mathbb{R}^n$ . Let  $S$  be a nonempty, closed, bounded, convex set. Then*

$$(\forall c \in \mathbb{R}^n), (\exists x(c) \in S) : c \in N_S(x(c))$$

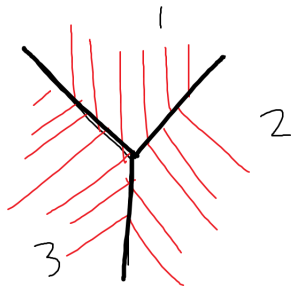
**Proof:** Let  $x(c)$  be the maximizer of  $c^T x$  over  $S$ . By the previous theorem and the Weierstrass' theorem,  $c \in N_S(x(c))$ . □

**Example** Suppose we take a triangle and write down its normal cone directions:



Given  $c \in \mathbb{R}^n$ ,  $f(x) = c^T x$  is maximized at one of three points:

Partition the space of  $\mathbb{R}^n$  into three cells, each corresponding to the normal cone at a different vertex. Then depending on which cell  $c$  is in, choose the corresponding vertex at which the normal cone is located. The previous theorem then shows that  $c^T x$  is maximized at that vertex.



1. If  $c \in$  , then  $\chi(c) =$  top vertex
2. If  $c \in$  , then  $\chi(c) =$  bottom right vertex
3. If  $c \in$  , then  $\chi(c) =$  bottom left vertex.

## 2 Normal cone of a polyhedral set

In this class we care most about the normal cone of a polyhedron.

**Theorem 3** Let  $A \in \mathbb{R}^{m \times n}$  and let  $b \in \mathbb{R}^m$ . Consider the polyhedron  $Q(A, b) = \{x | Ax \leq b\}$ . Suppose  $x \in Q(A, b)$ , then  $N_{Q(A, b)}(x) = \{A^T y | y \in \mathbb{R}^m \text{ such that } y \geq 0 \text{ and } y^T(b - Ax) = 0\}$ .

The condition that  $y^T(b - Ax)$  is equivalent to the complementarity conditions  $b_i - a_i x > 0 \implies y_i = 0$  and  $y_i > 0 \implies b_i - a_i x = 0$ . This fact is actually the key to linear programming duality.

**Proof:**

Let  $Y = \{A^T y | y \geq 0, y^T(b - Ax) = 0\}$ .

“ $\supseteq$ ”:

Suppose  $y \in \mathbb{R}^m, y^T(b - Ax) = 0$ . Let  $z \in Q(A, b)$  and expand:

$$y^T A(z - x) = \sum_{i: a_i x \neq b_i} y_i a_i (z - x) + \sum_{j: a_j x = b_j} y_j a_j (z - x)$$

By assumption  $y_i = 0$  if  $a_i x \neq b_i$ , so the first sum is zero. We're left with

$$= \sum_{j: a_j x = b_j} y_j (a_j z - b_j) \leq 0,$$

which implies that  $A^T y \in N_{Q(A,b)}$ .

“ $\subseteq$ ”:

Suppose  $g \in N_{Q(A,b)}(x)$  and  $g \notin Y$ . We wish to reach a contradiction.

By the separating hyperplane theorem, there exists a vector  $\hat{a} \in \mathbb{R} \setminus \{0\}$  and a number  $\hat{b} \in \mathbb{R}$  s.t.

$$(\forall w \in Y) \hat{a}^T w < \hat{b} < \hat{a}^T g$$

Clearly,  $0 \in Y$ . Therefore,  $0 = \hat{a}^T 0 < \hat{b}$ , i.e.,  $\hat{b} > 0$ .

Moreover, because  $A^T = [a_1^T \ \dots \ a_m^T]$ , where  $a_i$  is the  $i$ th row vector of  $A$ , we find that for any  $i$  such that  $a_i x = b_i$ , we have

$$(\forall \lambda \geq 0) \lambda \hat{a}^T a_i^T = \hat{a}^T A \lambda e_i < \hat{b},$$

where  $e_i$  denotes the all-zeros vector with a 1 in the  $i$ th component. Note that  $A^T \lambda e_i$  is in the  $Y$  set because it's in the range of  $A^T y$  for an appropriate choice of  $y$ . Thus, that  $(\forall \lambda > 0)$ ,  $\hat{a}^T A^T \lambda e_i < \frac{\hat{b}}{\lambda}$ . Therefore take  $\lambda \rightarrow \infty$  and note that  $\frac{\hat{b}}{\lambda} \rightarrow 0$  to show that  $\hat{a}^T a_i^T \leq 0$ .

Now, for each  $\epsilon > 0$ , define  $z(\epsilon) = x + \epsilon \hat{a}$ . We claim that  $\exists \epsilon > 0$  s.t.

1.  $z(\epsilon) \in Q(A, b)$ ; and
2.  $g^T(z(\epsilon) - x) > \epsilon \hat{b} > 0$  which contradicts the inclusion  $g \in N_{Q(A,b)}(x)$ .

**Proof of 1:** Suppose that  $a_i x = b_i$ , which implies that  $a_i \hat{a} \leq 0$ . Then for all  $\epsilon > 0$ ,  $a_i z(\epsilon) = a_i(x + \epsilon \hat{a}) \leq a_i x \leq b_i$ .

If  $a_i x < b_i$  and  $a_i \hat{a} \leq 0$ , then a similar argument shows that for all  $\epsilon > 0$ , we have  $a_i z(\epsilon) \leq b_i$ .

On the other hand, if  $a_i x < b_i$  and  $a_i \hat{a} > 0$ , then for all  $0 < \epsilon < \frac{b_i - a_i x}{a_i \hat{a}}$ , we have

$$\begin{aligned} a_i z(\epsilon) &= a_i x + \epsilon a_i \hat{a} \\ &\leq a_i x + \frac{b_i - a_i x}{a_i \hat{a}} \\ &= b_i. \end{aligned}$$

Therefore, we set  $\epsilon = \min \left\{ \frac{b_i - a_i x}{a_i \hat{a}} \mid a_i \hat{a} > 0 \right\}$  and find that  $z(\epsilon) \in Q(A, b)$ .

**Proof of 2:** By assumption, take  $\hat{a}^T g > \hat{b} > 0$ , which implies that

$$g^T(z(\epsilon) - x) = g^T(x + \epsilon \hat{a} - x) = \epsilon g^T \hat{a} > \epsilon \hat{b} > 0$$

□

Normal cones arising in dual linear programs are now easy to compute.

**Theorem 4** Let  $c \in \mathbb{R}^m$  and let  $Y = \{y \in \mathbb{R}^m \mid y \geq 0, A^T y = c\}$ , and let  $y \in Y$ . Then, we have

$$N_Y(y) = \{-b \mid \exists x \in \mathbb{R}^n \text{ with } Ax \leq b, y^T(b - Ax) = 0\}$$

**Proof:** Write:

$$Y = \left\{ y \mid \begin{bmatrix} -I \\ A^T \\ -A^T \end{bmatrix} y \leq \begin{bmatrix} 0 \\ c \\ -c \end{bmatrix} \right\}.$$

Then by previous theorem:

$$N_Y(y) = \left\{ \begin{bmatrix} -I & A^T & -A^T \end{bmatrix} \begin{bmatrix} s \\ t \\ w \end{bmatrix} \mid \begin{bmatrix} s \\ t \\ w \end{bmatrix} \geq 0, \begin{bmatrix} s \\ t \\ w \end{bmatrix}^T \left( \begin{bmatrix} -I \\ A^T \\ -A^T \end{bmatrix} y - \begin{bmatrix} 0 \\ c \\ -c \end{bmatrix} \right) \geq 0 \right\}$$

Equivalently:

$$= \{-s + At - Aw \mid s, t, w \geq 0, s^T(-y) + t^T(A^T y - c) + w^T(-A^T y + c) = 0\}$$

Replace  $t, w$  with  $z = t - w$  and let  $A^T y = c$ , to get

$$\begin{aligned} &= \{-s + Az \mid s \geq 0, s^T y = 0\} \\ &= \{\bar{b} \mid \bar{b} \leq Az, y^T(\bar{b} - Az) = 0\}, \end{aligned}$$

where we solved for  $s$  in this expression and used the identity that  $s = Az - b \geq 0$ . Replace  $z$  with  $-x$  and  $\bar{b}$  by  $-b$  to get.

$$= \{-b \mid Ax \leq b, y^T(b - Ax) = 0\}.$$

□

### 3 Strong Duality

Consider the primal linear program

$$p^* = \text{maximize}_{Ax \leq b} c^T x$$

and the dual linear program

$$d^* = \text{minimize}_{\substack{A^T y = c \\ y \geq 0}} b^T y$$

Then exactly one of the following holds:

- Both the primal and dual problems are infeasible, i.e.,  $p^* = -\infty$  and  $d^* = \infty$ .
- The maximizer of the primal and the minimizer of the dual exist, i.e.,  $p^*$  and  $d^*$  are finite and  $p^* = d^*$ .
- The primal objective is unbounded over the feasible set and the dual is infeasible, i.e.,  $d^* = \infty$  and  $p^* = \infty$ .
- The dual objective is unbounded over the feasible set and the primal is infeasible, i.e.,  $p^* = -\infty$  and  $d^* = -\infty$ .

**Proof: Proof of strong duality**

- Part 1: See Homework 2 where you provided an example of primal and dual both being infeasible.
- Part 2:

- (a) Suppose that  $p^*$  is finite and let  $x^*$  maximizes the primal program. Then, by Theorem 1, we have  $c \in N_{Q(a,b)}(x^*) = \{A^T y \mid y \geq 0, y^T(b - Ax^*) = 0\}$ . So we can take any such  $y$  from the normal cone and write  $c = A^T y^*$  where  $y^* \geq 0, (y^*)^T(b - Ax^*) = 0$ . Then  $y^*$  is dual feasible and

$$p^* = c^T x^* = (A^T y^*)^T x^* = (y^*)^T Ax^* = (y^*)^T b$$

Thus by weak duality,  $y^*$  is dual optimal and  $p^* = d^*$ .

- (b) Suppose  $d^*$  is finite and let  $y^*$  be a minimizer of the dual. In order to apply Theorem 1, we need to replace the dual objective by  $-b^T y$ . Then

$$-b \in N_{\{y \mid A^T y = c, y \geq 0\}}(y^*) = \{-\bar{b} \mid A\bar{x} \leq \bar{b}, (y^*)^T(\bar{b} - A\bar{x})\}$$

Choose any  $x^*$  such that  $Ax^* \leq b$  and  $(y^*)^T(b - Ax^*) = 0$ . Then

$$d^* = (y^*)^T b = (y^*)^T (Ax^*) = (A^T y^*) x^* = c^T x^*.$$

Thus, by weak duality, we conclude that  $x^*$  is primal optimal and  $p^* = d^*$ .

The rest of the proof will be presented in the next lecture.

□